# Intelligent Transport Systems (ITS) in Hong Kong: Recent Development and Future Applications

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### **Agenda**

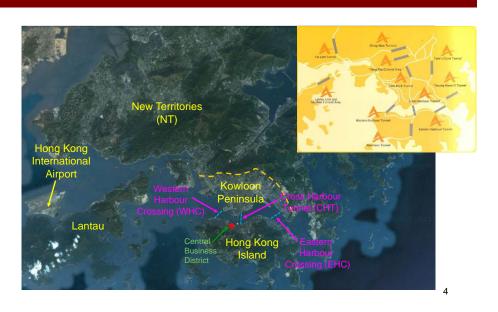
- Background
- Four Recent ITS Applications in Hong Kong
- Potential ITS Applications
- Q&A

### Hong Kong - A high density populated city



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### Geography of Hong Kong



### Background

- Population: ~ 7 million
- Total area: 1104 km², about 20% land developed
- Car ownership: 52 per 1000 people, about 10% of the US figure, despite a similar level of GDP
- Urban density: 34,000 persons/km²
- In comparison: LA 3,144;

Taipei - 9,650; Tokyo - 7,100; Bangkok - 1,301

- 12 million daily trips, ~10% of car trips
- Road length = 2 076km
- No. of licensed vehicle = 613 000
- Tag in circulation is about 250,000 tags out of 613,000 licensed vehicles in Hong Kong in March 2011 (87,000 penetration of tags of 174,000 commercial vehicles is about 50%).

### **Better Use of New Technologies**

### **Objective**



### **Better Use of New Technologies**

### **Intelligent Transport Systems**

- ◆ Passenger information
- ◆ Driver information
- Traffic Management and Information Centre
- Common payment systems e.g. the Octopus card

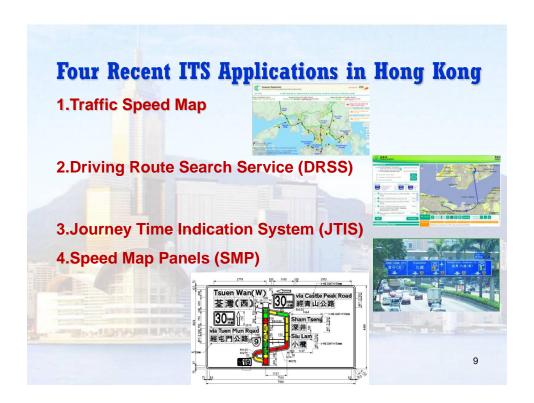


What are Intelligent Transport Systems (ITS)?



Deployment of advanced information and telecommunication technologies to enhance the safety, efficiency, reliability, user and environmental friendliness of the transport system

Source: The Final Report of the ITS Strategy Review (2001)



# 1. Traffic Speed Map Project Information

Client: Transport Department of HKSAR

Project Manager: Electrical & Mechanical Services

Department of HKSAR

Contractor: Autotoll Limited

Sub-contractor: Hong Kong Polytechnic University

Launch of Service: January 2007

Update: May 2010

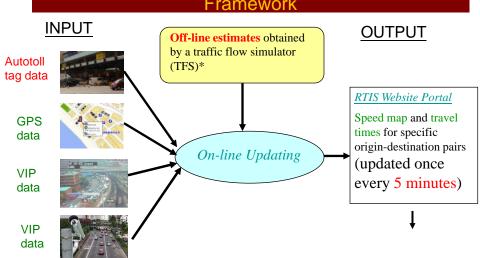
### 1. Traffic Speed Map



### (<a href="http://tis.td.gov.hk/rtis/ttis/index/main\_partial.jsp">http://tis.td.gov.hk/rtis/ttis/index/main\_partial.jsp</a>)

- · Launched in Hong Kong Transport Department's website in January 2007
- Recently updated in May 2010 with use of the latest road network in Hong Kong

# Real-time Traffic Information System (RTIS) Framework



<sup>\*</sup> Lam W.H.K., Chan K.S. and Shi J.W.Z (2002) A Traffic Flow Simulator for Short-term Travel Time Forecasting. Journal of Advanced Transportation, 36(3), 265-291.

### **Presentation Summary of Traffic Speed Map**

- · Accuracy level of traffic speed colour
- Validation methods
  - Test car survey on road segments without CCTV cameras
  - Observation survey based on CCTV images
- · Validation results
  - Test car survey
  - Observation survey

Title: Using automatic vehicle identification data for travel time estimation in Hong Kong

Author(s): Tam Mei Lam; Lam William H. K.

Source: TRANSPORTMETRICA Volume: 4 Issue: 3 Pages: 179-194 Published: 2008

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### **Accuracy Level of Traffic Speed Map**

Under normal condition, 90% probability of observed average speed falling within the specified speed range throughout the whole day.

For example, 08:40-08:45:

On a road segment of a major route:

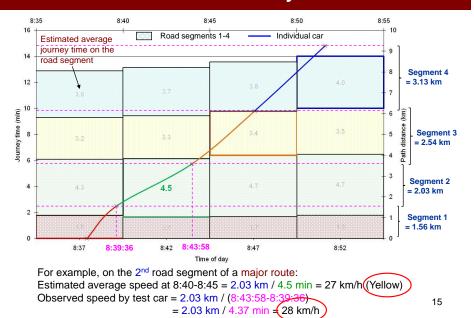
Observed average speed = 28 km/h

Estimated speed colour = Yellow

Estimated speed colour = Red X

Major Routes Traffic Speed

### **Test Car Surveys**



### **Validation Results of Test Car Surveys**

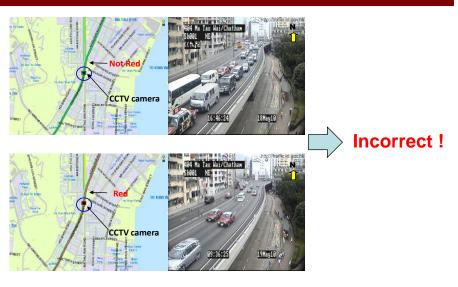
Survey day: one typical weekday (Tue, Wed or Thu) in May 2010 for each path

Survey period: one peak and one non-peak periods (each period was 2 hours)

Survey route: 5 selected routes in urban area of Hong Kong

Route	Number of observed average speeds on the segments along the path	Number of accurate speed color estimates	Accuracy	Achievement of targeted accuracy level	
Α	48	45	93.8%	✓	
В	95	89	93.7%	✓	
С	80	77	96.3%	<b>✓</b>	
D	112	109	97.3%	<b>✓</b>	
E	160	149	93.1%	<b>✓</b>	16

### **Observation Surveys on CCTV Images**



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### **Results of Observation Surveys**

- Survey day: 14 May (Fri) 24 May (Mon) 2010, excluding public holiday of 21 May 2010 (a total of 10 days)
- Survey period: 08:00-20:00 (12 hours)
- Frequency of checking : 10-minute interval
- Location: 30 selected locations with CCTV cameras
- Results:
  - all locations with accuracy of ≥ 90%
  - 29 locations (96.7%) with accuracy of ≥ 95%
  - 27 locations (90.0%) with accuracy of ≥ 97%
  - 17 locations (56.7%) with accuracy of ≥ 99%

### 2. Driving Route Search Service (DRSS)



## Presentation Summary of Driving Route Search Service (DRSS)

- Project information
- · Criteria of route search
  - Shortest travel time
  - Lowest toll
  - Shortest distance
- · Features of DRSS
  - Incorporation of real-time traffic speed data
  - Road network information
  - Special traffic news

### 2. DRSS Project Information

Client: Transport Department of HKSAR

Project Manager: Electrical & Mechanical Services

Department of HKSAR

Contractor: Autotoll Limited

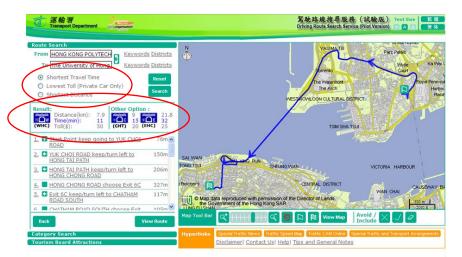
Commencement: April 2008

Launch of Service: April 2010

Sub-contractor: Hong Kong Polytechnic University

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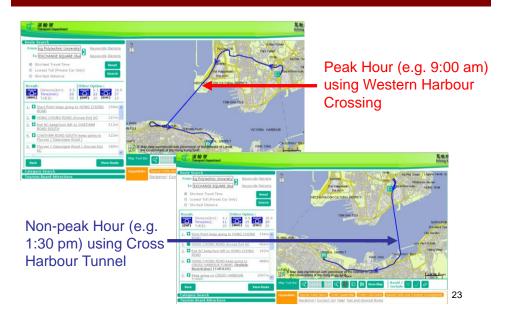
### **Route Search**



(http://drss.td.gov.hk/drss)

Launched in Hong Kong Transport Department's website in April 2010

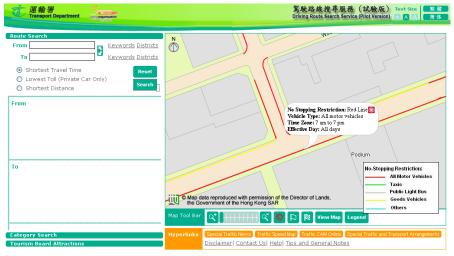
### **Incorporation of Real-time Traffic Speed Data**



### **Road Network Information (Parking)**



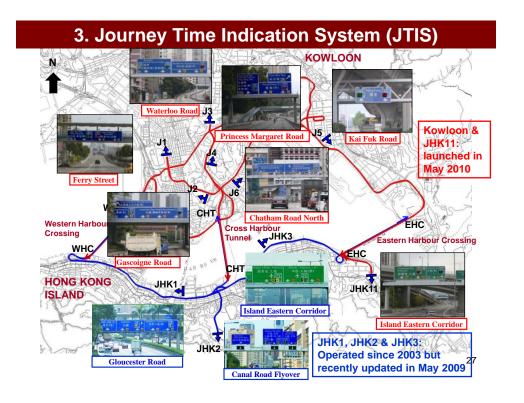
### **Road Network Information (No-Stopping Restriction)**



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### **Special Traffic News**





# Presentation Summary of Journey Time Indication System (JTIS)

- Project information
- Two different types of traffic detectors
  - 1. Automatic vehicle identification (AVI) detector using RFID for electron toll collection
  - 2. Spot speed detector (e.g. Autoscope)
- Accuracy requirement of journey time estimates
   Within +/- 20% errors with a compliance of 95% throughout the survey periods within two survey days (a weekday and a weekend) for each selected path.
- Validation results on 13 selected paths

### 3. JTIS Project Information

Client: Transport Department of HKSAR

Project Manager: Electrical & Mechanical Services

Department of HKSAR

Contractor: Autotoll Limited

Contract Period:

Implementation: October 2008

Launch of Service: May 2009 (Hong Kong Island: JHK1-3),

May 2010 (Kowloon and JHK11)

Defects Liability Period: 12 months

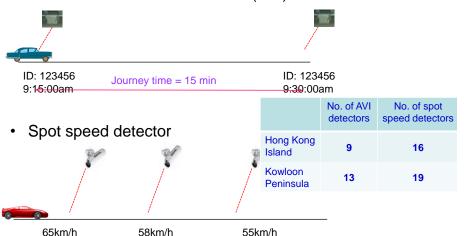
Operation & Maintenance (O&M): 8 years

Sub-contractor: Hong Kong Polytechnic University

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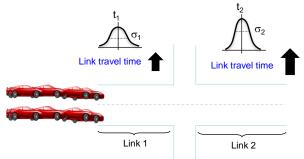
### **Two Types of Traffic Detectors**

· Automatic vehicle identification (AVI) detector



### **Offline Travel Time Estimates**

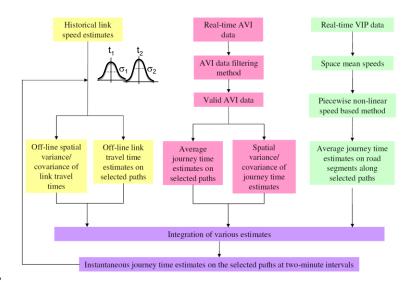
- ❖ Average link travel time estimates (t₁, t₂)
- Spatial variance  $(\sigma_1^2, \sigma_2^2)$  and covariance  $(\sigma_1\sigma_2)$  relationships of link travel times



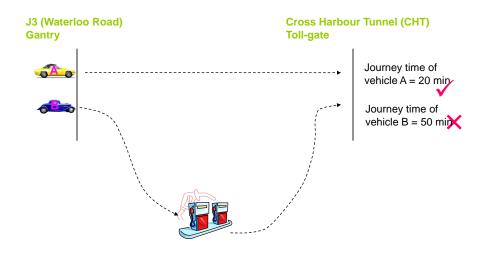
Title: Real-Time Estimation of Arterial Travel Times with Spatial Travel Time Covariance Relationships Author(s): Chan K. S.; Lam William H. K.; Tam Mei Lam

Source: TRANSPORTATION RESEARCH RECORD Issue: 2121 Pages: 102-109 Published: 2009

### Algorithm for Journey Time Estimation



### **AVI Data Filtering**



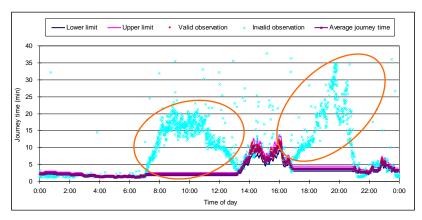
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### **AVI Data Filtering Methods**

	JTIS	TransGuide	TranStar	Transmit
Interval	2 minutes	2 minutes	30 seconds	15 minutes
Thresholds of valid time window	Stochastic (dependent on various factors at the previous time intervals)	Fixed (±20% of mean journey time at the previous time interval t-1)	Fixed (±20% of mean journey time at interval t-1)	Fixed (±X% of mean journey time at interval t-1, X is defined by users)
Applications in	Hong Kong	San Antonio, USA	Houston, USA	New York/ New Jersey, USA

Tam M.L. and Lam W.H.K. (2008) Using Automatic Vehicle Identification Data for Travel Time Estimation in Hong Kong. Transportmetrica, Vol. 4, No. 3, 179-194.

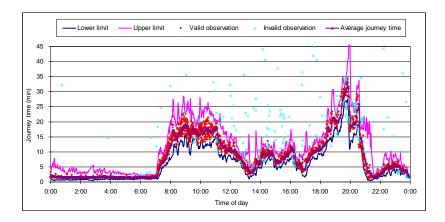
AVI Data Filtering Method for Generating Valid Time Windows using Fixed Threshold (e.g. +/-20% of mean journey times at previous time interval t-1)



J4 (Princess Margaret Road) – Cross Harbour Tunnel (Toll gate) on 5 Feb 2010 (Friday)

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# JTIS Data Filtering Method for Generating Stochastic Valid Time Windows



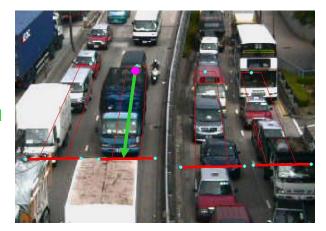
J4 (Princess Margaret Road) – Cross Harbour Tunnel (Toll gate) on 5 Feb 2010 (Friday)

### Speed Data Collected by Autoscopes

Time mean speed



Space mean speed



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### Speed-based Method for Estimating Journey Time

· Average speed method

Piecewise linear speed based method

thod 500m 500m 20m

Piecewise non-linear speed based method (with consideration of covariance relationship of link travel times/speeds)



### **Integration of Different Journey Time Estimates**

- · Instantaneous journey time estimates
  - = A \* journey time estimated by valid Autotoll tag data
    - + B \* journey time estimated by Autoscope data
    - + C \* offline journey time estimates
- Weights of A and B are dependent on sample sizes of valid Autotoll tag and Autoscope data, respectively
- Offline estimates are the lowest priority (C=1-A-B)

Title: Application of automatic vehicle identification technology for real-time journey time estimation

Author(s): Tam Mei Lam; Lam William H. K.

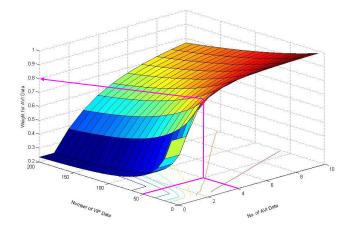
Source: INFORMATION FUSION Volume: 12 Issue: 1 Pages: 11-19

Published: JAN 2011

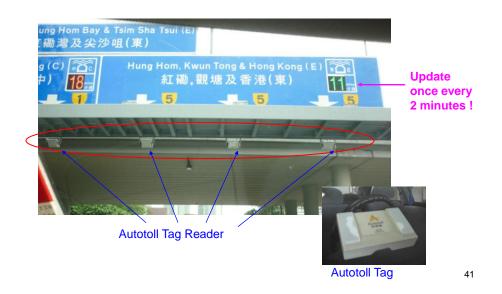
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### Integration of Different Traffic Data

Mainly dependent on sample sizes of AVI tag data



# Automatic Vehicle Identification (AVI) Detector – Autotoll Tag Reader

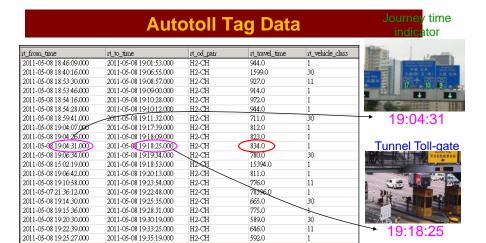


Automatic Vehicle Identification (AVI) Detector
– Autotoll Tag Reader (RFID technology)





**Autotoll Tag** 



Journey time from journey time indicator to tunnel toll-gate

 $= 19:18:25 - 19:04:31 = 13 \min 54 \sec = 834 \sec$ 

Tag in circulation is about **250,000 tags** out of 613,000 licensed vehicles in Hong Kong in March 2011 (**87,000** penetration of tags of 174,000 commercial vehicles is about **50%**).

### Real-time Data collected by Autotoll Tag Reader





11 tolled links in HK

Tag in circulation is about 250,000 tags out of 613,000 licensed vehicles in Hong Kong in March 2011 (87,000 penetration of tags of 174,000 commercial vehicles is about 50%).

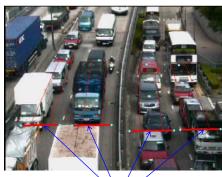
# Spot Speed Detector – Video Image Processing (VIP) Technology



Video detector: Autoscope

Data Collected: Traffic counts, time

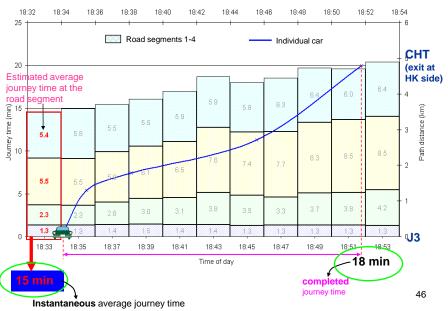
mean speed and space mean speed, etc.



Detection zones of Autoscope

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### JTIS Instantaneous Average Journey Time Estimates



### **Performance Criterion for Journey Time Validation**

 Within +/- 20% errors with a compliance of 95% throughout the survey periods within two survey days (a weekday and a weekend) for each selected path.

For example, JHK1-CHT at 09:00:00-09:01:59 on Sunday:

Observed instantaneous journey time = 4 min (50 km/h)

Estimated instantaneous journey time = 5 min (40 km/h) cross Harbour

Estimation error =  $(5-4)/4 \times 100\% = 25\% > 20\%$ 

CHT Exit (Kowloon)

Cross Harbour Tunnel

Path no. 1: JHK1 - CHT = 3.35 km

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### **Validation Results**

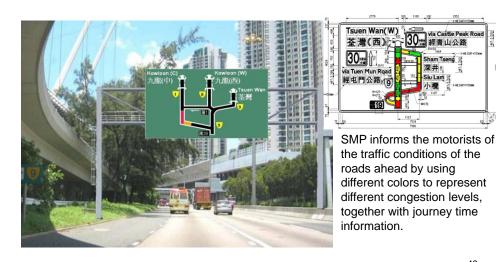
JTIS (Hong Kong Island)			JTIS (Kowloon Peninsula)				
Path No.	Selected path	No. of samples	Accuracy*	Path No.	Selected path	No. of samples	Accuracy*
1	JHK1-CHT	94	97.9%	1	J1-CHT	159	98.1%
2	JHK1-EHC	91	98.9%	2	J1-WHC	117	98.3%
3	JHK2-CHT	120	95.0%	3	J2-CHT	78	96.2%
4	JHK2-EHC	102	97.1%	4	J2-EHC	203	99.0%
5	JHK2-WHC	110	95.5%	5	J3-CHT	110	96.4%
6	JHK3-CHT	103	95.1%	6	J3-EHC	137	100.0%
7	JHK3-WHC	114	98.3%	7	J3-WHC	80	98.8%
8	JHK11-CHT	90	97.8%	8	J4-CHT	86	95.3%
9	JHK11-EHC	119	99.2%	9	J4-WHC	132	98.5%
The			مالا	10	J5-CHT	187	97.3%
The requirement of the targeted accuracy level is achieved.				11	Ј5-ЕНС	184	98.4%
				12	J6-CHT	93	95.7%
				13	J6-WHC	114	96.5%

\*Percentage of samples within ± 20% errors throughout the survey periods in the validation.

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JHK1-JHK3, JHK11 and J1-J6 are the journey time indicators in Hong Kong Island and Kowloon Peninsula, respectively.

Abbreviation: CHT – Cross Harbor Tunnel; EHC – Eastern Harbor Crossing; WHC – Western Harbor Crossing.

### 4. Speed Map Panels (SMP) in the New Territories



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### **Presentation Summary of Speed Map Panels**

- Project information
- Location and layout of SMP
- Two different types of traffic detectors
  - 1. Spot speed detector (e.g. Autoscope)
  - 2. Automatic vehicle identification (AVI) detector using Automatic license plate recognition technology



GH5286 REG\_NUMBER: CONFIDENCE: VESNAME: Fixed VES VES LOC: Gloucester Rd NORTHING: 2466490 208700 EASTING:

### **SMP Project Information**

Client: Transport Department of HKSAR

Project Manager: Mott MacDonald (HK) Limited

Contractor: Autotoll Limited

Contract Period:

Implementation: January 2010

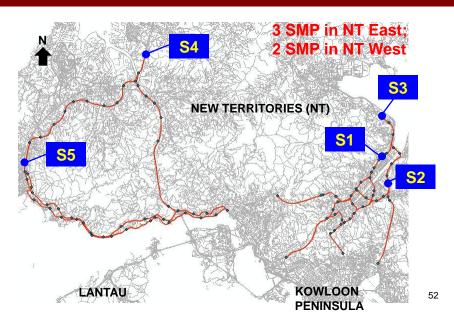
Expected Launch of Service: June 2012 Defects Liability Period: 12 months

Operation & Maintenance (O&M): 8 years

Sub-contractor: Hong Kong Polytechnic University

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### **Location of Five Speed Map Panels (SMP)**



# Speed Map Panel (S5) in NT West Tuen Mun Road Tuen Mun Road Touen Mun to Tsuen Wan West Distance from Tuen Mun to Tsuen Wan West:

### **Two Types of Traffic Detectors**

Castle Peak Road



<u>Link speed detector</u>: Automatic license plate recognition technology

via Tuen Mun Road = 17.5 km
via Castle Peak Road = 18.2 km

Spot speed detector: Video image processing technology 54

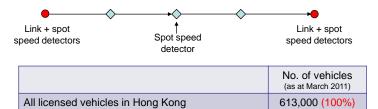
### **Two Types of Traffic Detectors**

- Link speed and spot speed detectors are installed at the starting and the end points of the path segments.
  - Longest path segment = 9.4 km
  - Shortest path segment = 1.1 km

Corporate vehicles (owned by limited companies)

Corporate vehicles with Autotoll tags

 Average spacing of spot speed detectors is not greater than 1.2 km.



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174,000 (28%)

87,000 (14%)

### Validation Approach for Journey Time and Traffic Speed Range Measurements

Floating car surveys

Day of Week:	1 weekday and 1 weekend (Sat or Sun)				
Survey Period:	08:00-11:00;	12:00-15:00;	17:00-20:00		
No. of Selected Paths: 13	9 (NTE) + 4 (NTW) = 11 for journey time and traf speed range validation				
	2 (NTE) for traffic speed range validation only				
Test Cars:	5-10 test cars for each selected path were estimated based on the path distance and the cycle time of test cars on each path				

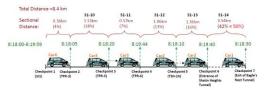
### Distance of the 13 Selected Paths in SMP

Path No.	Selected Path	Path Distance (km),	Path No.	Selected Path	Path Distance (km)
1	SJ1-SMT	7.7	10	SJ4-TKTL	12.0
2	SJ1-TSCA	8.4	11	SJ4-TKTM	26.9
3	SJ1-LRT	7.5	12	SJ5-TWTM	16.9
4	SJ2-TSCA	9.7	13	SJ5-TWCP	17.3
5	SJ2-LRT	7.1			
6	SJ2-TCT	5.4			
7	SJ3-TSCA	11.9			
8	SJ3-LRT	11.0			
9	SJ3-TCT	10.2			

Distance of the longest selected path in JTISK (J3-EH) = 12.3km

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### Journey time surveys



- No. of test cars were estimated based on the path distance and the cycle time of the test car
- Allocate at least one test car on each road segment of the selected path simultaneously
- Similar to take a snapshot at each road segment of the selected path at the same time
- Test cars are travelled at similar speed of surrounding traffic (y = 0)
  - y = No. of vehicles overtaking test car No. of vehicles passed by test car y  $\propto$  q\*(v-v\_w)/v where v=speed of test car, v\_w=speed of traffic stream, q=flow If y=0, then v=v\_w
- The targeted accuracy level of the journey time estimates is within +/- 20% errors with a compliance of 95% throughout the survey periods within two survey days (a weekday and a weekend) for each
- selected path.

### Colour codes for Traffic Speed Ranges

Major routes:

```
Red: 0-25km/h; Amber: 25-50km/h; Green: > 50km/h
```

• Urban roads:

```
Red: 0-15km/h; Amber: 15-30km/h; Green: > 30km/h
```

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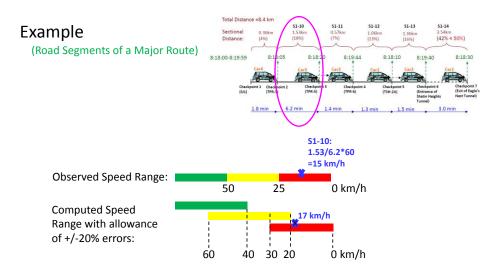
### Performance Criterion for Traffic Speed Range

- The targeted accuracy level of the computed speed range for SMP should be fallen within +/- 20% with a compliance of 95%.
- Thus, the computed speed ranges for two types of routes become:

### **Major Routes**

```
Red: 0-30km/h; Amber: 20-60km/h, Green: >40km/h
Urban Roads
```

Red: 0-18km/h; Amber: 12-36km/h, Green: >24km/h





### **Technologies for Incident Management**



Feasibility Study on Deploying Advanced Technologies in Incident Management

- Executive Summary February 2010

http://www.td.gov.hk/filemanager/en/publication/executive%20summary\_english.pdf

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### **Traffic Accident on Major Road**



13:40PM on Nov 19 2008.

### **Incident Detection**



Time Interval (t)	Predicted Travel Speed ( Y <sub>7</sub> ) (km/h)	Observed Travel Speed ( <b>X</b> <sub>t</sub> ) (km/h)	Relative Difference of Travel Speed (Y <sub>T</sub> -X <sub>t</sub> )/Y <sub>T</sub>	Threshold of Relative Difference of Travel Speed	
10:10-10:11	54.0	60.0	-0.1	0.4	
10:12-10:13 (Estimated incident occurrence time)	54.0	50.0	0.1 Time to 4 min	detect: 0.4 Time to alarm:	•
10:14-10:15	54.0	8.0	0.9	0.4	4
10:16-10:17	54.0	4.6	0.9	0.4 Alarm	
10:18-10:19	54.0	17.0	0.7	0.4	
:	:	:	:	: 💉	4
10:36-10:37	54.0	10.0	0.8	0.4	
10:37-10:38	54.0	57.3	-0.1	0.4	

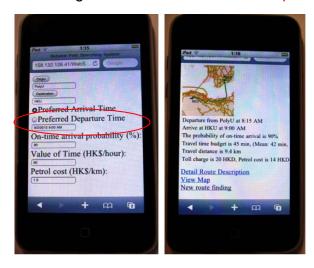
Notes: (1) Alarm is given when the relative difference of travel speed at two successive time intervals exceeds the threshold value.

(2)  $Y_T$  is referred to the predicted travel speed at the time interval of incident occurred.

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### **Route Guidance**

• Reliable routing service with on-time arrival probability



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### **Reliable Route Searching System**



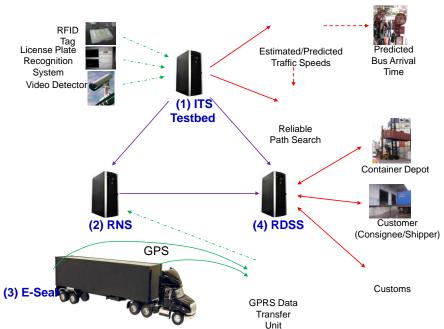
Title: Reliable shortest path finding in stoch astic networks with spatial correlated link travel times

Author(s): Chen Bi Yu; Lam William H. K.; Sumalee Agachai; et al.

Source: INTERNATIONAL JOURNAL OF GEOGRAPHICAL INFORMATION SCIENCE Volume: 26 Issue:

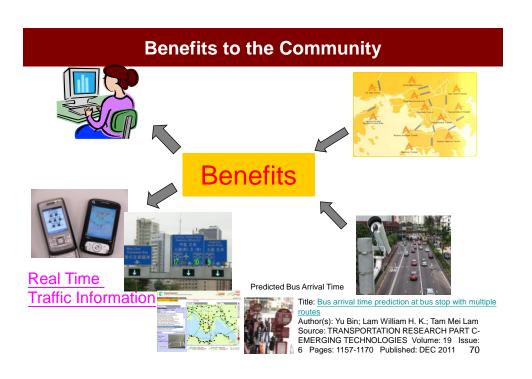
2 Pages: 365-386 Published: 2012

### **Overall System for Niche Areas ITS Project**



### **Intelligent Transportation System Testbed**





### Website of ITS in Hong Kong

- http://www.td.gov.hk/en/transport\_in\_hong\_kong /its/its\_achievements/index.html
  - Journey Time Indication System
  - Traffic Speed Map
  - Area Traffic Control Systems
  - Traffic Control and Surveillance System
  - Closed Circuit Television Images on the Internet
  - Automatic Toll Collection System



- Octopus
- Electronic Parking Meters
- Red Light Cameras and Speed Enforcement Cameras
- Traffic Control Centre

\* An integrated real-time traffic database for ITS in Hong Kong. 71

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### -The End-



The 17th HKSTS International Conference 15-17 December, 2012, Hong Kong http://www.hksts.org







The 5<sup>th</sup> International Symposium on Transportation Network Reliability (INSTR) 18-19 December, 2012, Hong Kong
<a href="http://www.instr2012.org">http://www.instr2012.org</a>
<sub>73</sub>